

Figure 1: RF power reflected from the RF cavity. Here $\beta=3.4$ and $V_{RF}=117\text{kV}$. The reflected power was not stable at over the current with minimum reflection power.

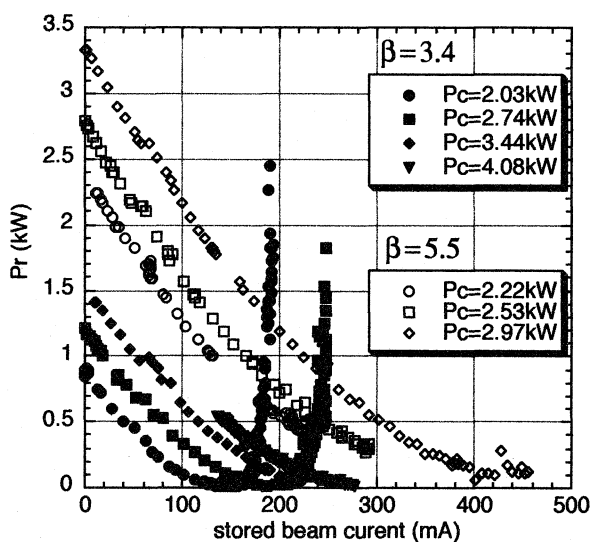


Figure 2: RF power reflected from the RF cavity (P_r) with $\beta=3.4$ and $\beta=5.5$ for various cavity power (P_c).

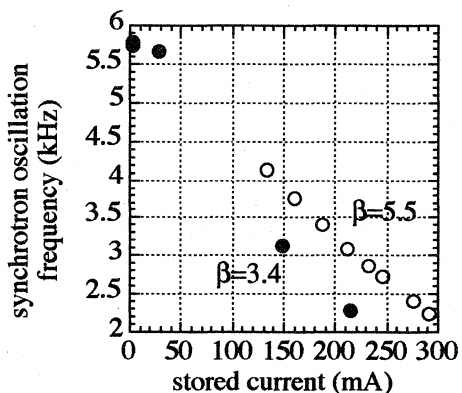


Figure 3: Synchrotron oscillation frequency shift by the beam loading. The open circles with $\beta=3.4$ and the shaded circles with $\beta=5.5$, both with $V_{RF}=107\text{kV}$.

2.2 Feedback Parameter

The next problem was the time constant of the low-level feedback control. Because the f_s was still low at the high beam current, the automatic voltage level control

(ALC) would enhance the phase modulation and excite the coherent synchrotron oscillation [5].

The time constant of the ALC feedback loop was changed. The frequency response of the loop, at before and at after the change are shown in Fig. 4 [6]. The feedback module of NewSUBARU is the same as that of SPring-8, described by T. Nakamura *et al* [7]. The capacitance C of the Figures was named as C_L in ref.[7]. With the larger C the increase of the synchrotron oscillation amplitude at over 250mA disappeared as shown in Fig.5.

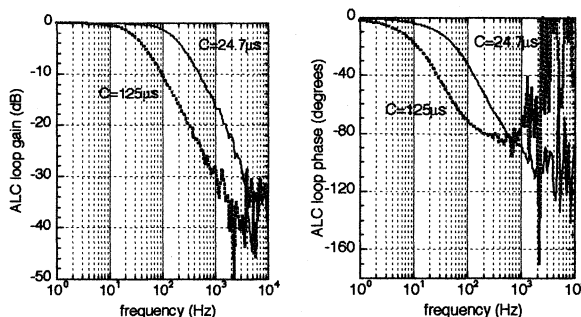


Figure 4: ALC feedback loop gain and phase with different capacitance, fast ($C=24.7\mu\text{F}$) and slow ($C=125\mu\text{F}$) case. The C is C_L in ref.[7].

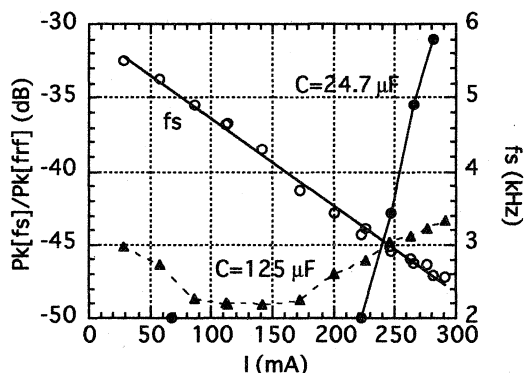


Figure 5: Relative amplitude of the synchrotron oscillation side band to the main RF acceleration frequency. The open circles are f_s . The shaded triangles and the circles were relative amplitude of f_s side bands, at before and at after the change. With the small capacitance C the synchrotron oscillation amplitude increased with $f_s < 3\text{kHz}$. At this time $V_{RF}=116\text{kV}$ and $\beta=5.5$.

2.3 Cavity Temperature

In fall of 2002 we found a correlation between the stored beam current and the cooling water temperature shown in Fig. 6 (a). In January 2003 the temperature was raised up to 36 degrees. The amplitudes of TM010 mode HOM, frequencies of 790MHz and 795MHz, decreased with the rise of the temperature (Fig. 6 (b)). This change enabled a beam accumulation up to 500mA.

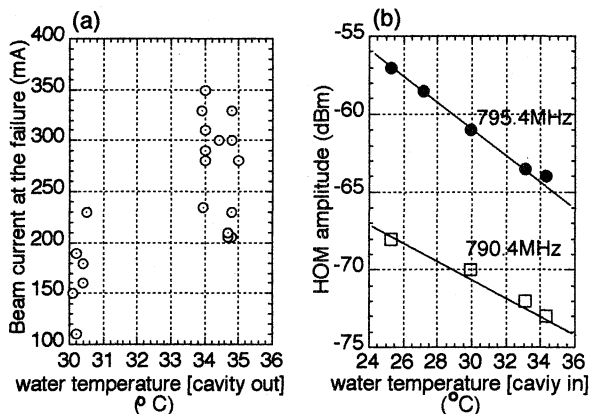


Figure 6: The effect of the water temperature.
 (a) Stored beam current vs. temperature of cooling water of the cavity. (b) Water temperature vs. HOM frequency.

2.4 Tuning Angle

The next problem was the horizontal instability maybe by HOM of 990 MHz or 790MHz. The HOM made the beam injection unstable at 50~100mA and caused an abrupt beam loss when the RF voltage was raised for the acceleration or during the acceleration. A small jittering of Pr is observed in Fig.1 at 50~100mA. A change of tuning angle of the cavity, from -5° to -21° eliminated the loss. Fig. 7 shows examples of the beam current during the acceleration from 1.0 GeV to 1.5 GeV. With the new angle parameter, we started the user operation at 1.5GeV at over 300mA.

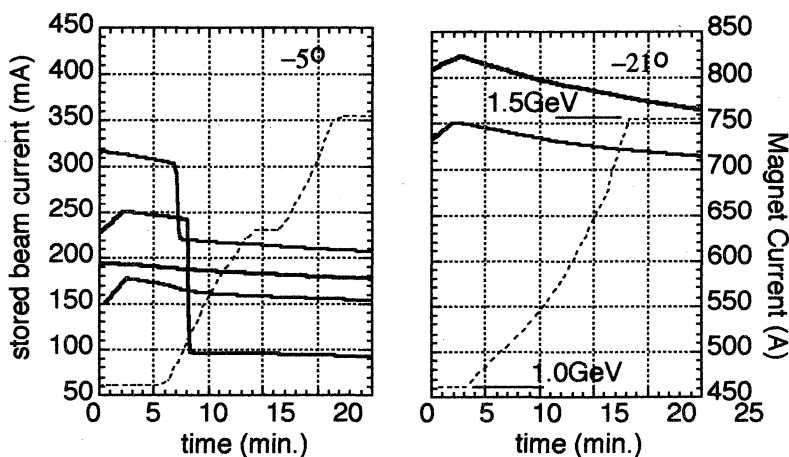


Figure 7: The stored beam current with the tuning angle of -5° (left) and -21° (right). The broken lines are current of bending magnet. The solid lines are examples of stored beam current during the acceleration.

3 SUMMARY

Some parameter tunings in these two years improved the beam behaviour at high beam current. However there still be a sudden and small beam loss at a high current for about once a month, which we do not have identified the reason.

In this summer we installed another remote controllable tuner, we call it HOM-tuner, and the beam commissioning with it has just started.

4 ACKNOWLEDGEMENT

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5 REFERENCES

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